

# Data Quality and feature extraction at scale with RoboSat.pink

@o\_courtin

@sotm 2019

# Goals

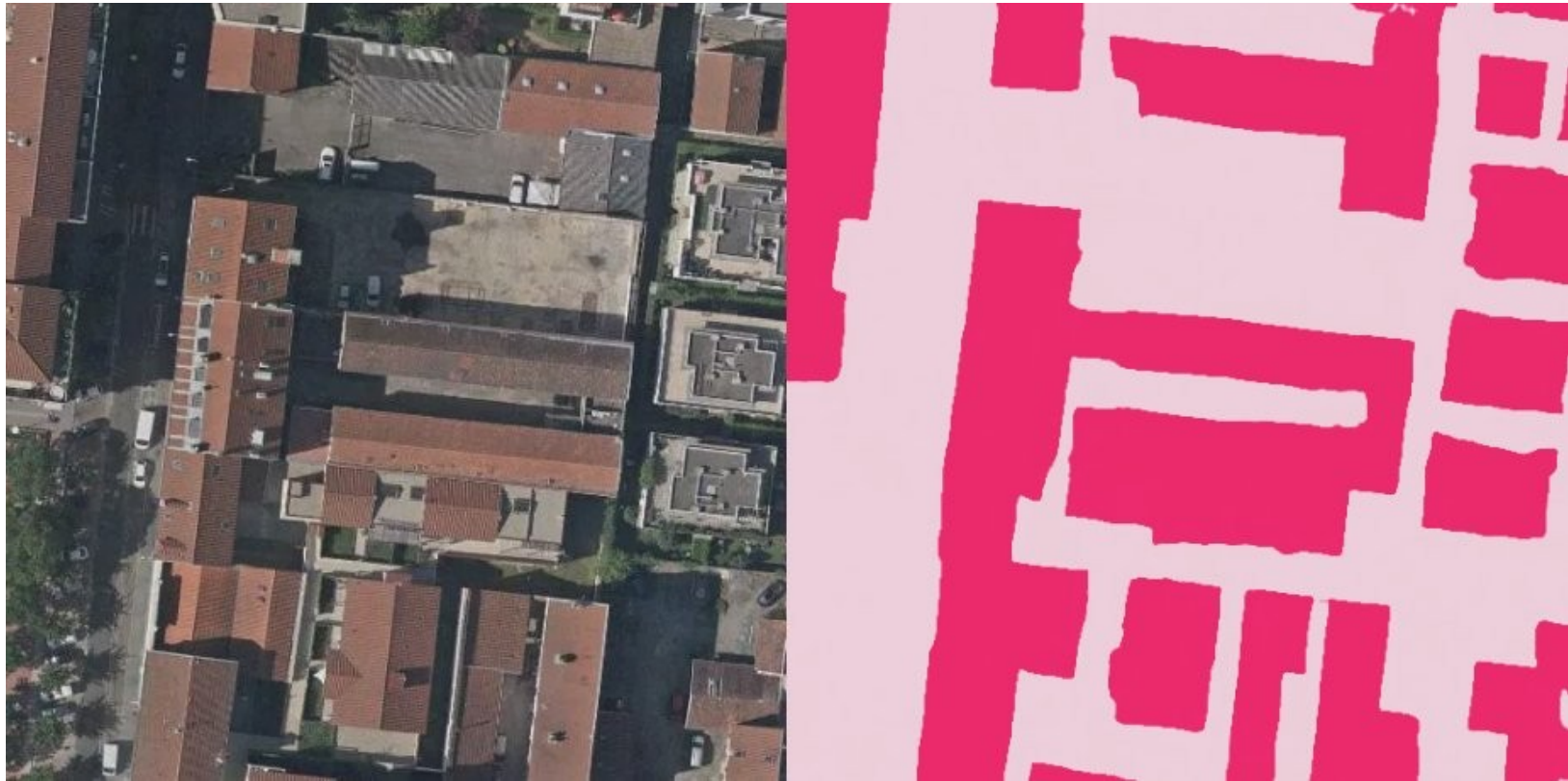
Detect inconsistencies between two DataSets

Train on a small area, predict on a larger one.

DataSet Quality Analysis

Change Detection highlighter

Features extraction

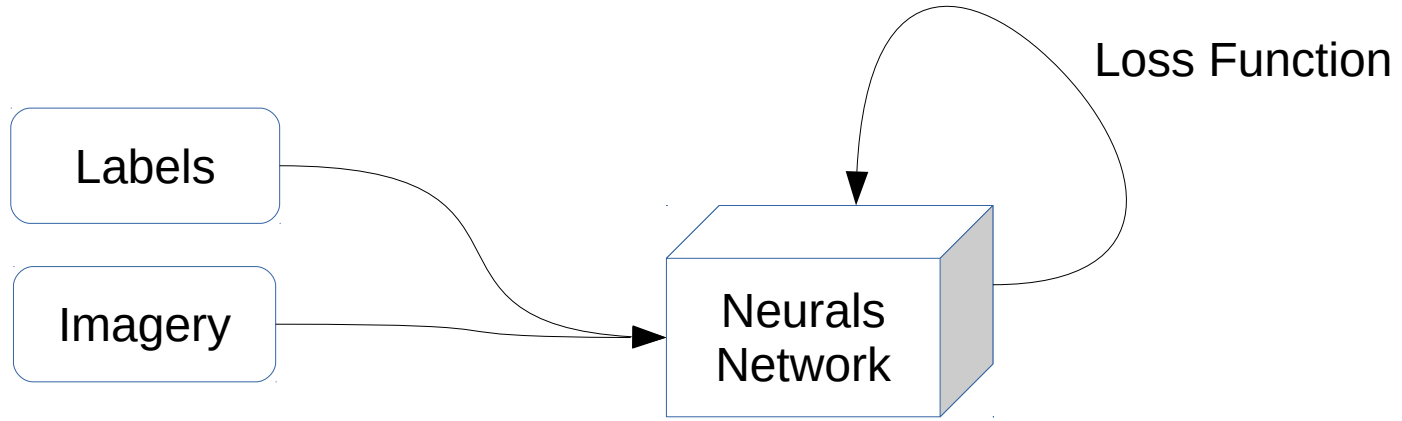


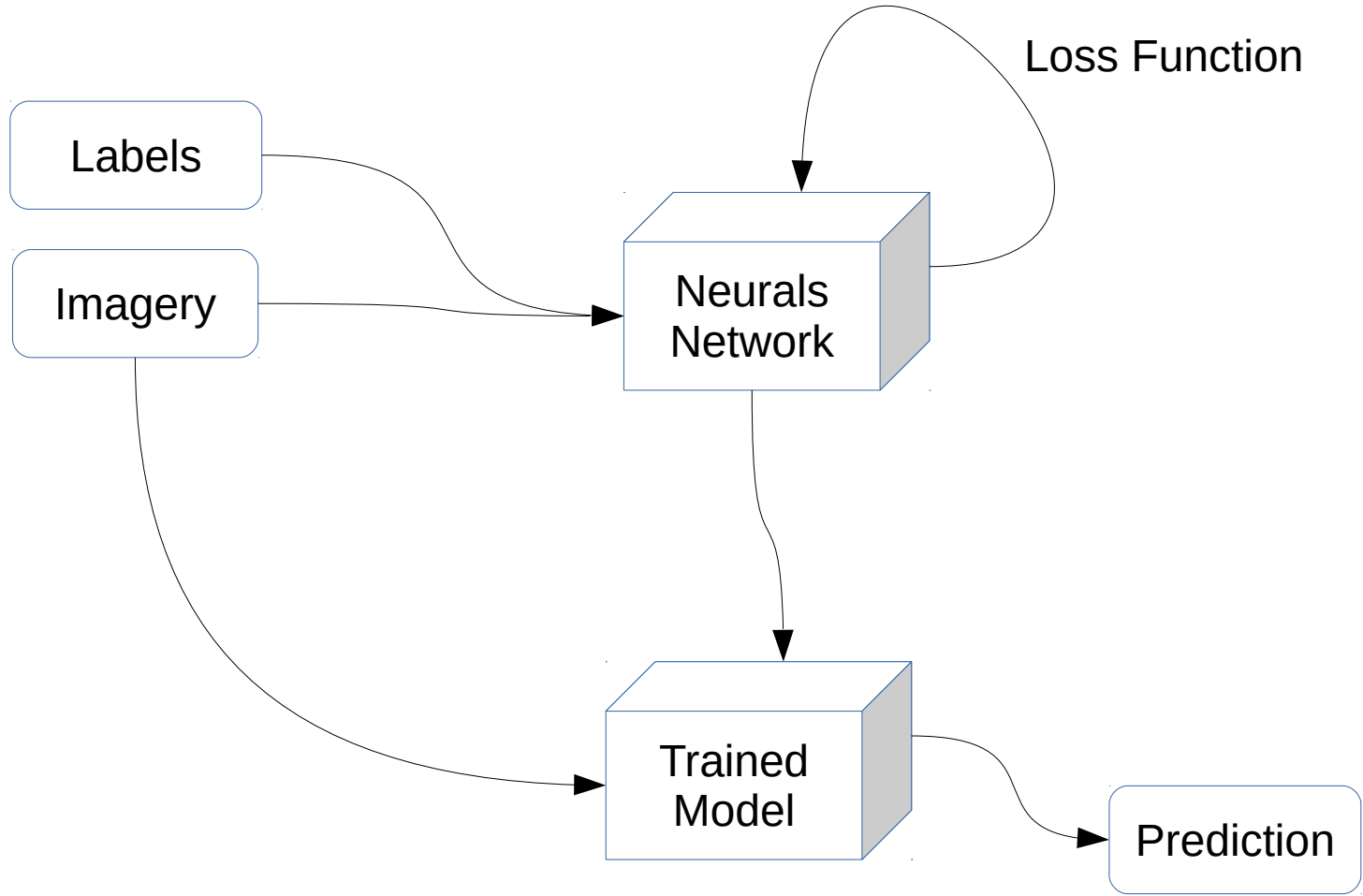
**RoboSat** **!=** **RoboSat.pink**

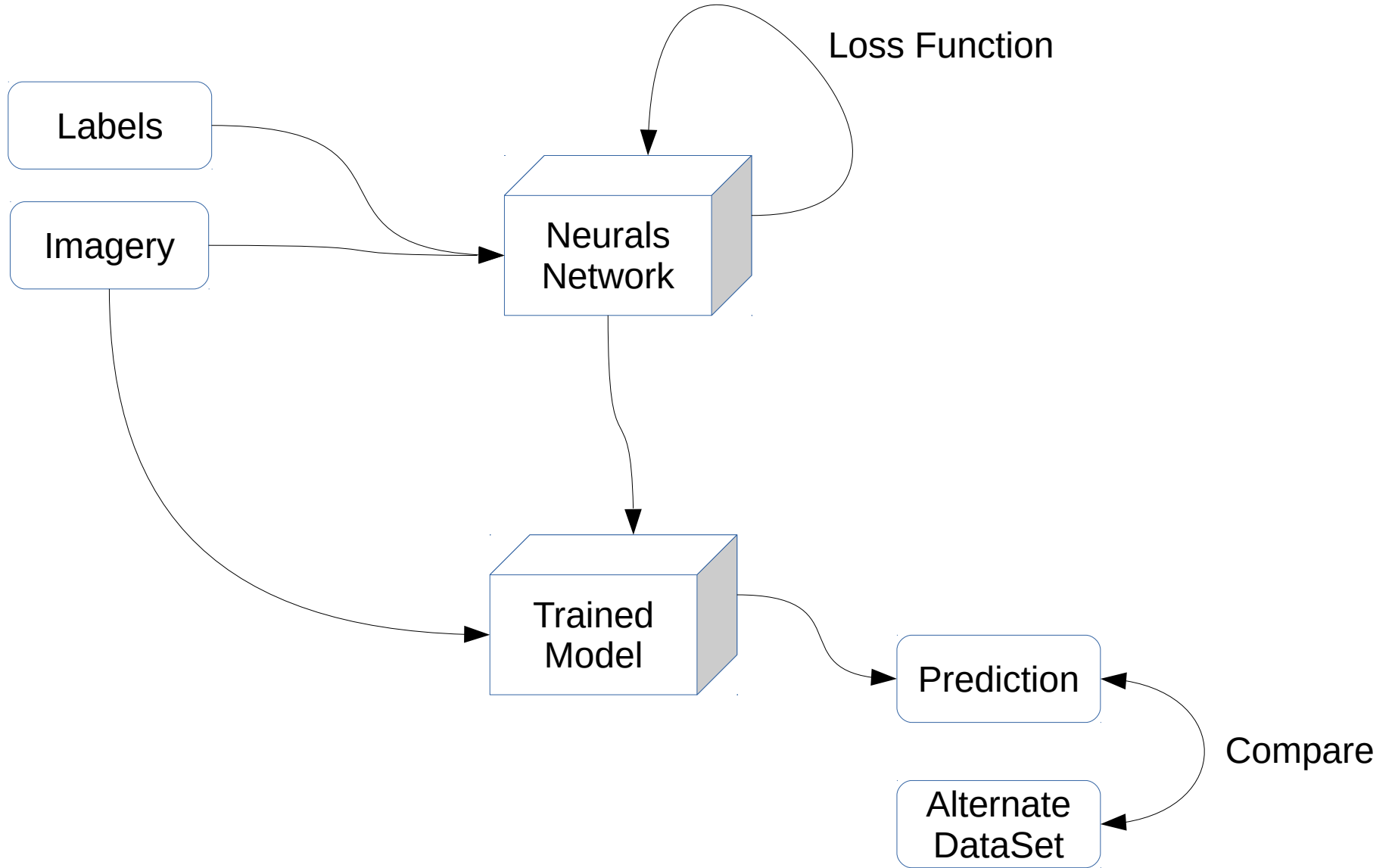
<https://github.com/mapbox/robosat>

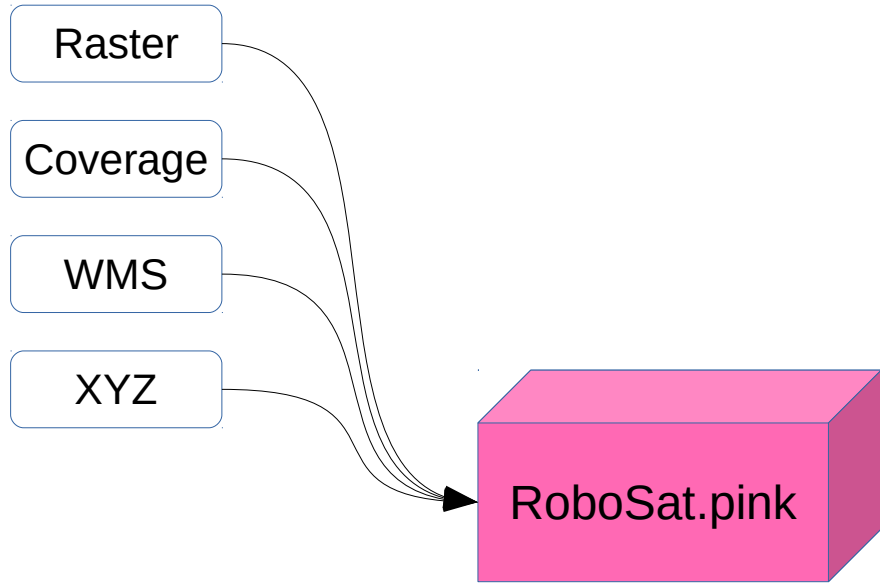
<https://github.com/datapink/robosat.pink>

<https://github.com/mapbox/robosat/issues/184>

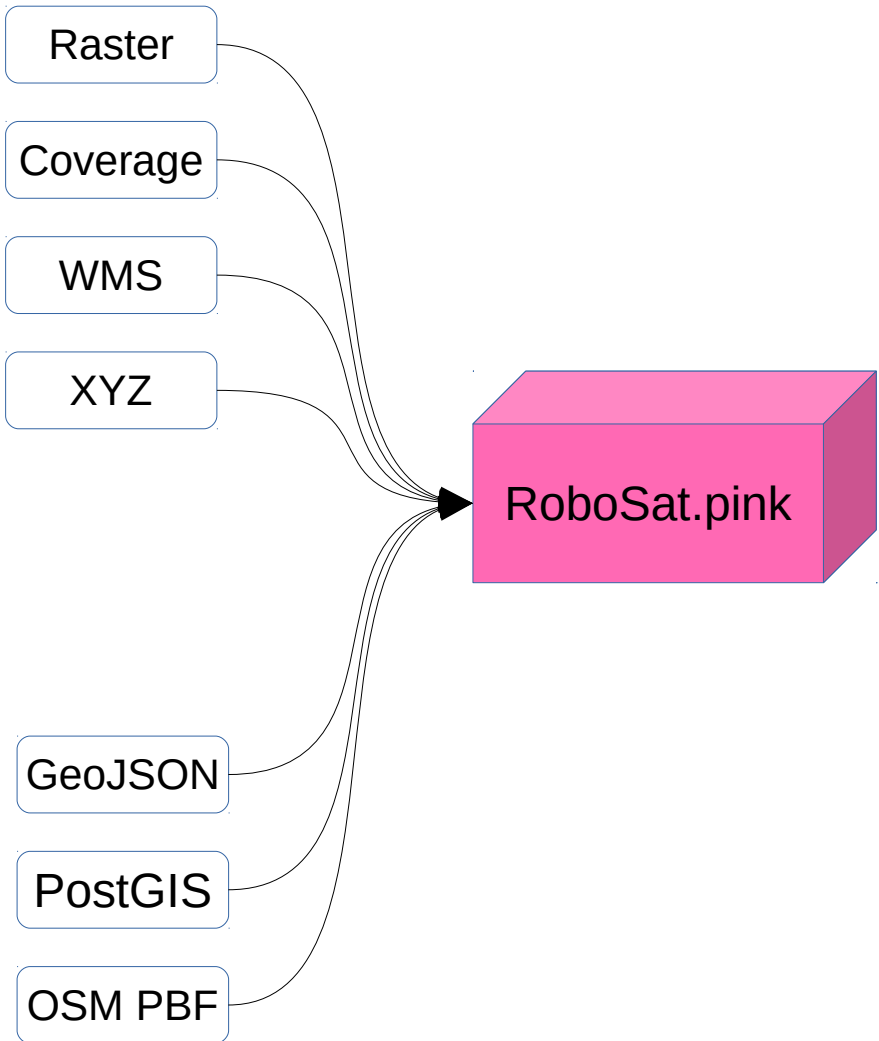


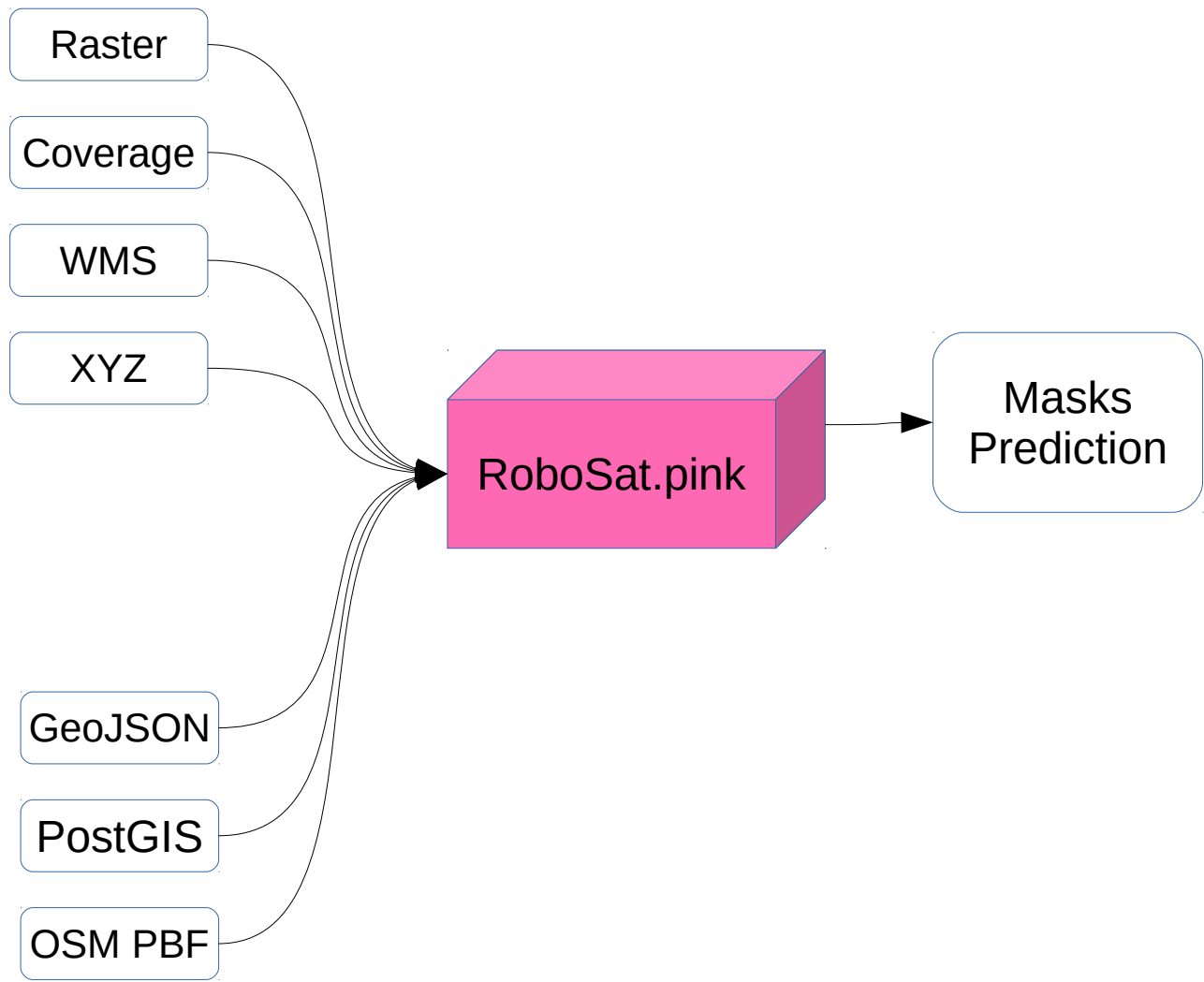


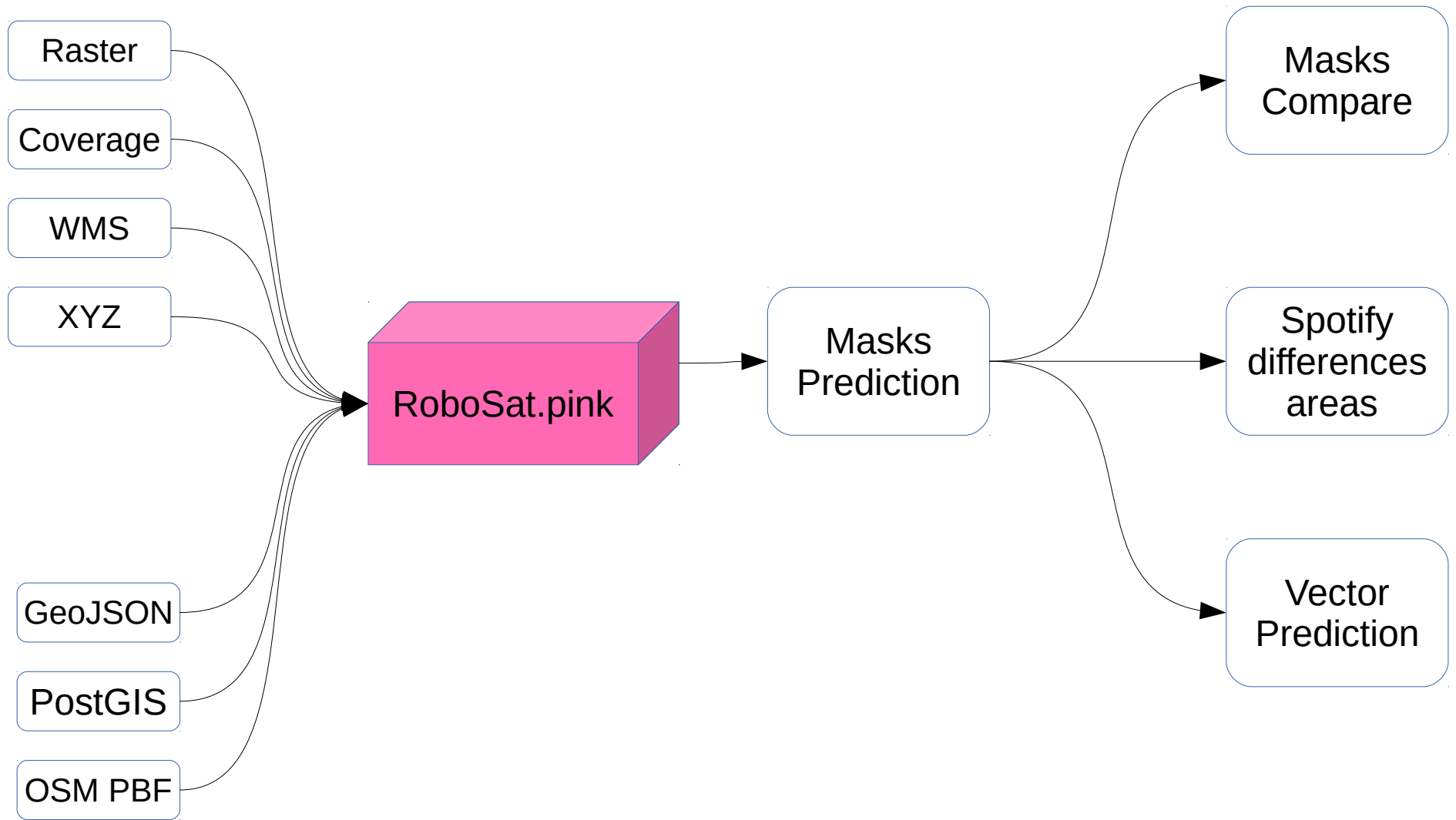












# Compare Predicts against alternate datasets



Pink : Predicted by trained model

Green : Alternate dataset

Grey : Both agree



Pink squares : Significant differences

# Command Line Interface

## Tools:

- `rsp cover` Generate a tiles covering, in csv format: X,Y,Z
- `rsp download` Downloads tiles from a remote server (XYZ, WMS, or TMS)
- `rsp extract` Extracts GeoJSON features from OpenStreetMap .pbf
- `rsp rasterize` Rasterize vector features (GeoJSON or PostGIS), to raster tiles
- `rsp subset` Filter images in a slippy map dir using a csv tiles cover
- `rsp tile` Tile raster coverage
- `rsp train` Trains a model on a dataset
- `rsp export` Export a model to ONNX or Torch JIT
- `rsp predict` Predict masks, from given inputs and an already trained model
- `rsp compare` Compute composite images and/or metrics to compare several XYZ dirs
- `rsp vectorize` Extract simplified GeoJSON features from segmentation masks
- `rsp info` Print RoboSat.pink version informations

# RoboSat.pink 101



<https://github.com/datapink/robosat.pink/blob/master/docs/101.md>

**Easy to deploy**

```
pip3 install RoboSat.pink
```

So all you need is :

- Imagery
- GPU
- Initial skills
- Labels



So all you need is :

- Imagery → *any file format readable by GDAL*
- GPU → *NVIDIA >= 8Go RAM*
- Initial skills → *GeoSpatial Data and CLI fluency*
- Labels → *that's often the key point*

# GeoSpatial OpenDataSets:

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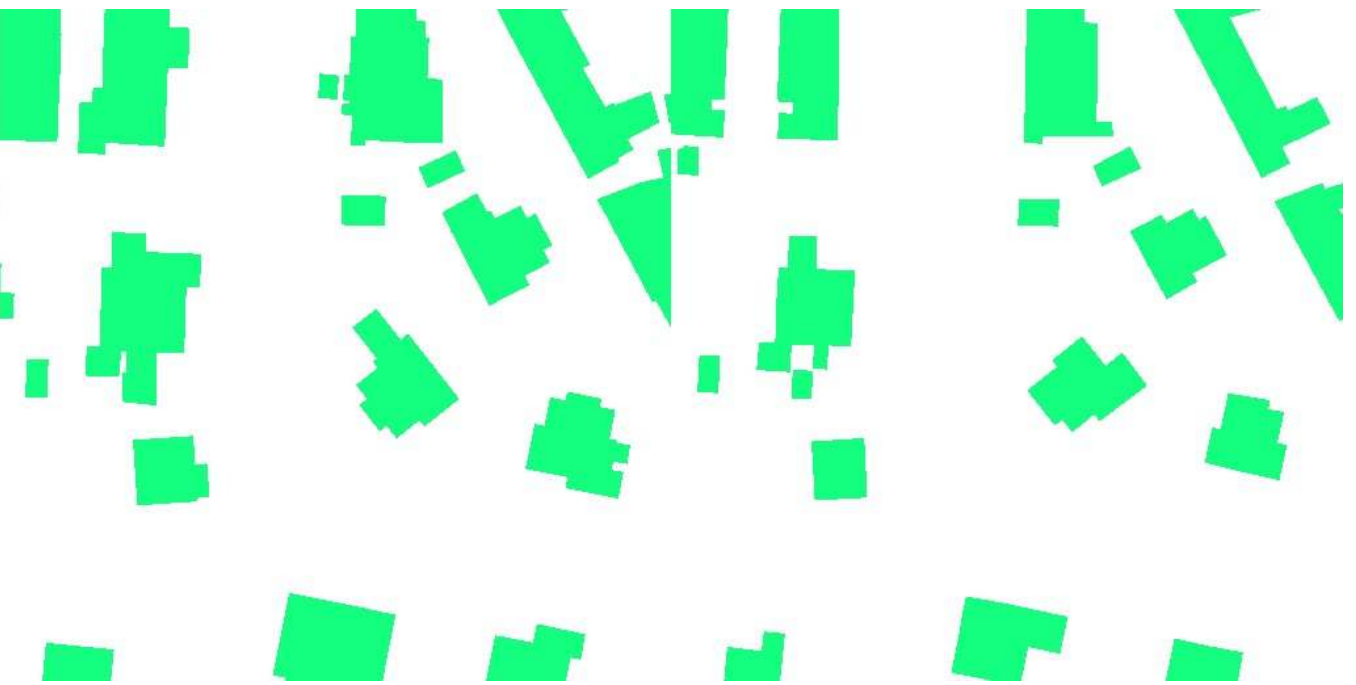
- [Christoph Rieke's Awesome Satellite Imagery Datasets](#)
- [Zhang Bin, Earth Observation OpenDataset blog](#)

<https://github.com/datapink/robosat.pink#geospatial-opendatasets>

# OSM not accurate enough for a good Training DataSet



Imagery



OpenData roofprints

OSM Building footprints

**G|GO**

# An Ideal OpenDataSet

OpenData Licence compliant

Worldwide landscapes representative

Retina TileSize 512px

Mixed resolutions, bands, and sensors imagery

Labels (building, roads, vegetation...) with pixel accuracy

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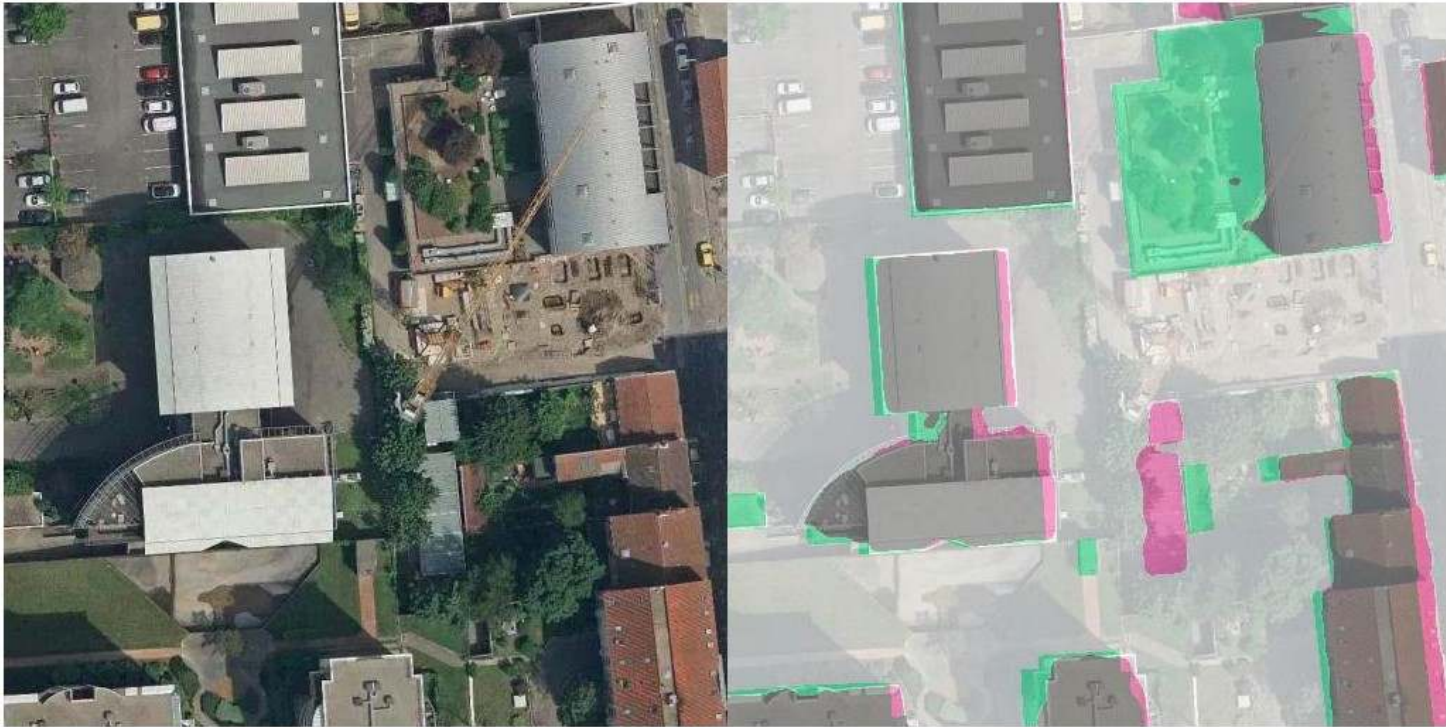
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TODAY 15 :00 : Machine Learning DataSet BoF in Kleiner Horsaal

# From OpenData to OpenDataSet



[https://github.com/datapink/robosat.pink/blob/master/docs/from\\_opendata\\_to\\_opendataset.md](https://github.com/datapink/robosat.pink/blob/master/docs/from_opendata_to_opendataset.md)



# Surface based semantic Loss



Image

Label

Cross Entropy

mIoU

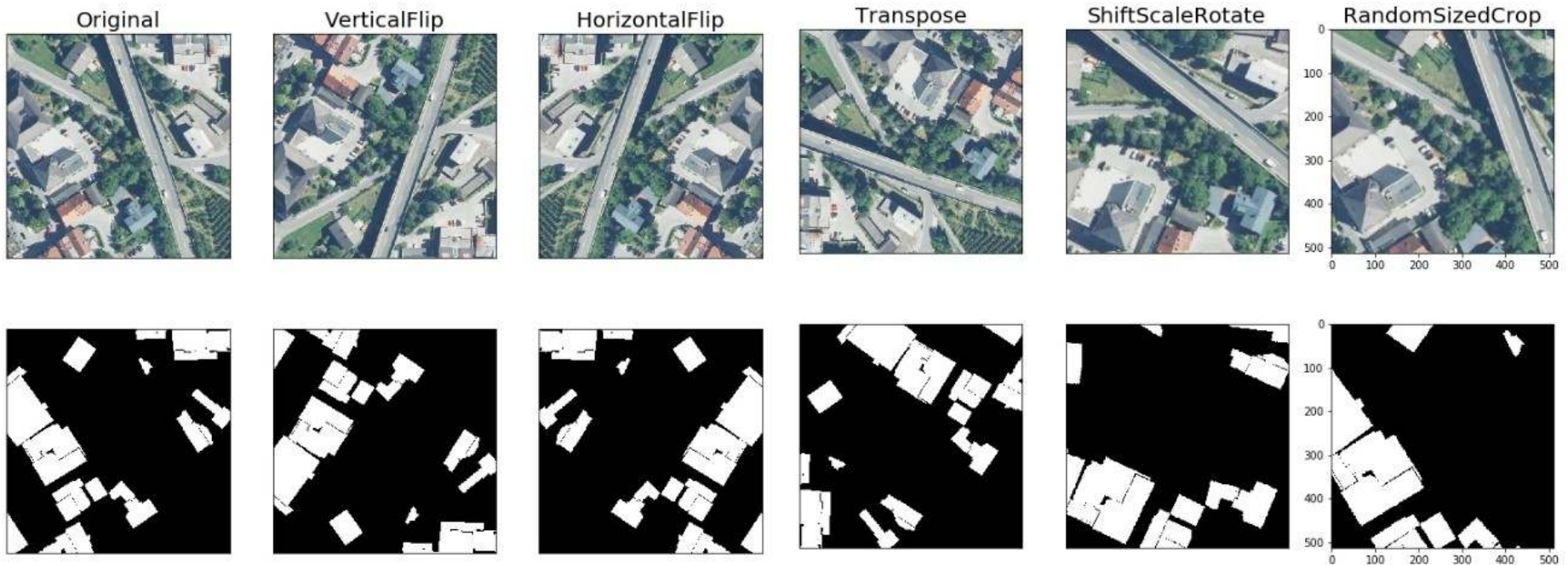
Lovasz

[http://www.cs.toronto.edu/~wenjie/papers/iccv17/mattyus\\_etal\\_iccv17.pdf](http://www.cs.toronto.edu/~wenjie/papers/iccv17/mattyus_etal_iccv17.pdf)

<http://www.cs.umanitoba.ca/~ywang/papers/isvc16.pdf>

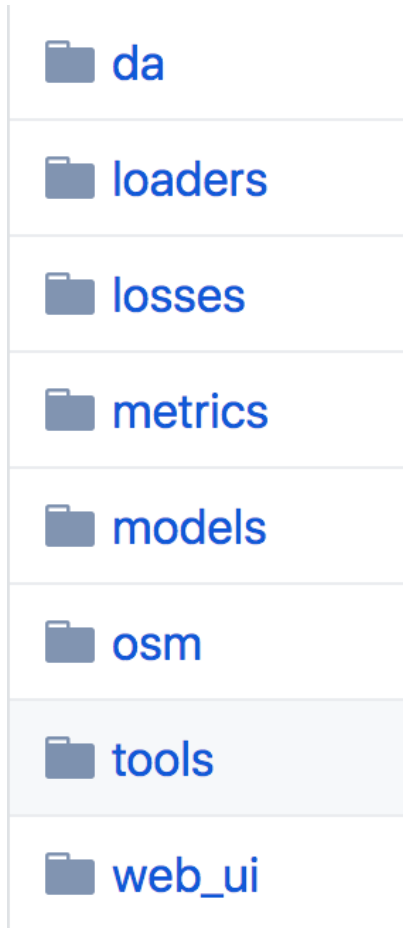
<https://arxiv.org/abs/1705.08790>

# Data Augmentations



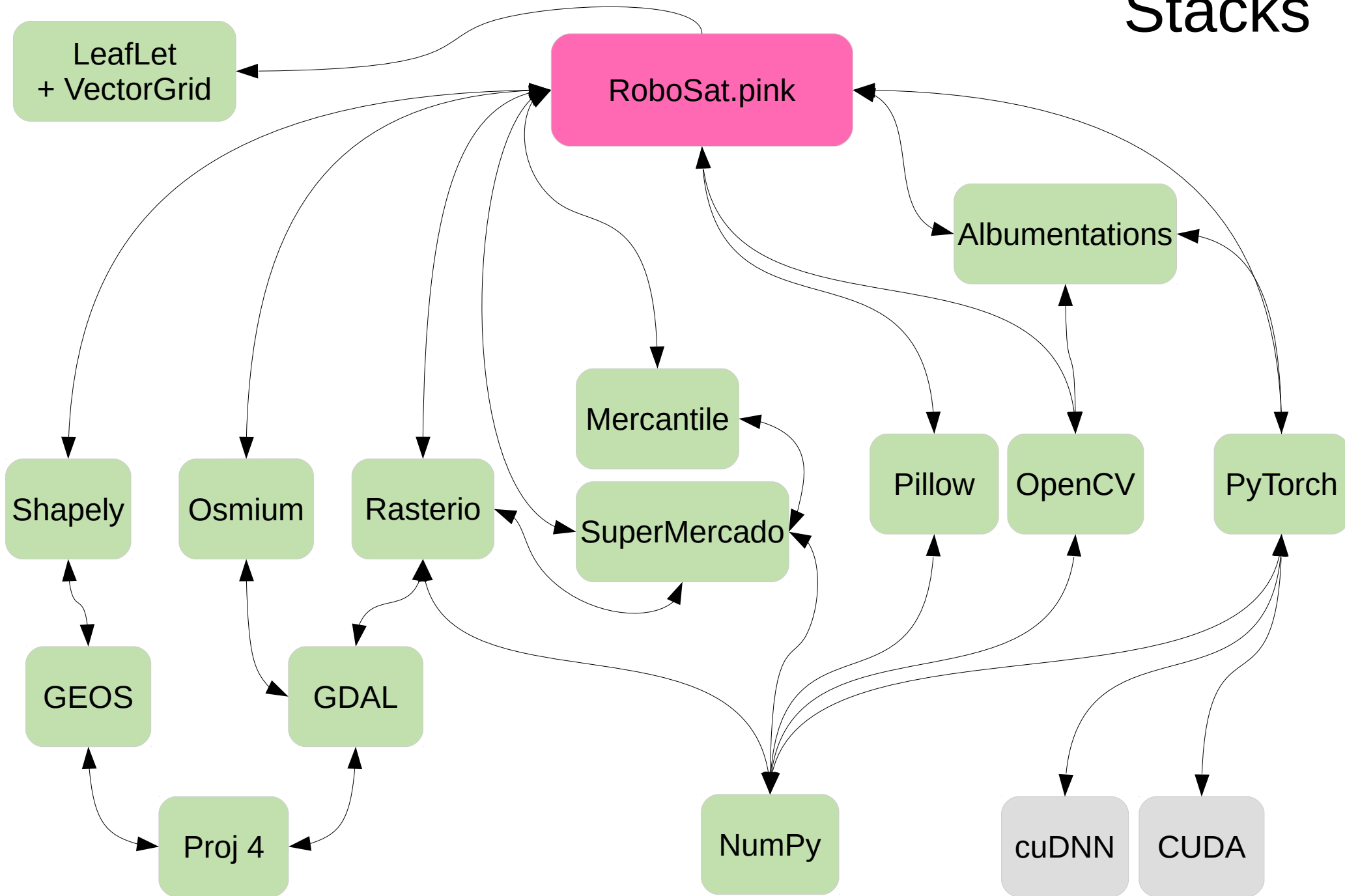
<https://arxiv.org/abs/1809.06839>  
<https://github.com/albu/albumentations>

# More than an application, an easy to extent framework







[https://github.com/datapink/robosat.pink/blob/master/docs/extensibility\\_by\\_design.md](https://github.com/datapink/robosat.pink/blob/master/docs/extensibility_by_design.md)

# Stacks



# Open Source

 **datapink / robosat.pink**  
forked from [ocourtin/robosat](#)

 Unwatch ▾ **8**  Star **59**  Fork **223**







[Code](#) [Issues 14](#) [Pull requests 0](#) [Security](#) [Insights](#) [Settings](#)

Computer Vision ecosystem for GeoSpatial Imagery [Edit](#)

[computer-vision](#) [semantic-segmentation](#) [aerial-imagery](#) [satellite-imagery](#) [deep-learning](#) [geospatial](#) [openstreetmap](#) [ecosystem](#)

[data-quality](#) [dataset-filtering](#) [change-detection](#) [feature-extraction](#) [remote-sensing](#) [earth-observation](#) [pytorch](#)

[Manage topics](#)

 **811** commits  **1** branch  **7** releases  **1** environment  **11** contributors  MIT

# Request For Funding

- Increase (again) prediction accuracy :
  - on low resolution imagery
  - even with few labels
  - feature extraction when they are (really) close
  - with multibands and Data Fusion
- Add support for :
  - MultiClass
  - Linear features extraction
  - PointCloud data support
  - StreetView Imagery
  - Time Series Imagery
  - OSM editor integration
- Improve (again) performances

<https://github.com/datapink/robosat.pink#requests-for-funding>

# Few performances Metrics

16 tiles = 4 Retina Tiles = 1Mp

rsp train	~5 Mp/s, -per epoch-
rsp tile	~5 Mp/s
rsp predict	~10 Mp/s
rsp compare	~50 Mp/s
rsp rasterize	~50 Mp/s
rsp vectorize	~50 Mp/s

8 cores CPU, single GPU (either RTX or V100), SSD

# How to scale it, or improve it again ?

rsp train	add more GPU, reduce dataset redundancy, improve model, loss or optimizer
rsp tile	add more CPU use raster compression
rsp predict	export model to ONNX or JIT, then use an high performance inference solution.



# Cost Effective GPU Servers



RTX



ThreadRipper

Own server

# Why performances matters ?

- Playful and Human Learning
- Time and money saver
- No Planet B

# Why using DeepLearning for Mapping ?

Easy to spotify at scale inconsistencies beetwen two datasets

If you provide good labels on a imagery,  
infere at scale on similar new imageries

So a time and money saver

# Why using RoboSat.pink ?

OSM easy integration (XYZ, Osmium, Leaflet...)

Build-in WebUI

High Performances

Easy to deploy

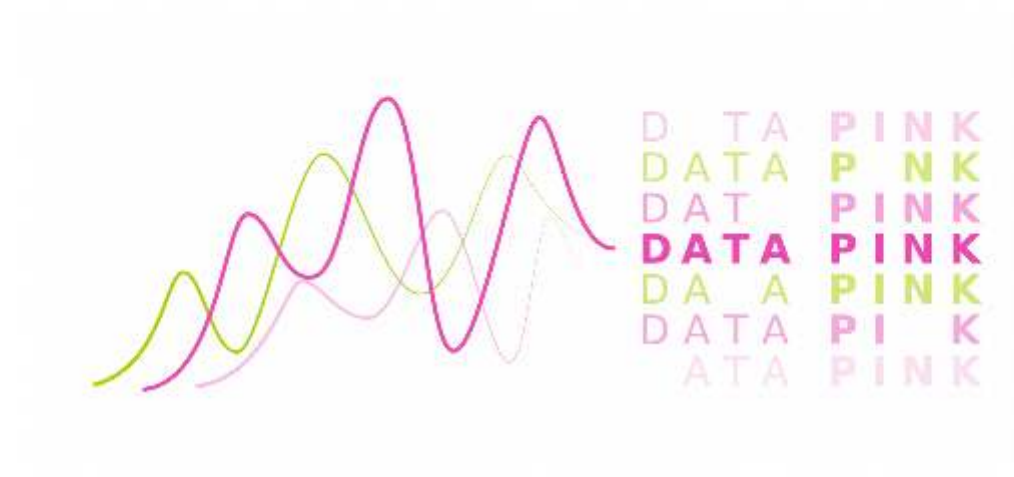
GIS Standards compliancy

Handle MultiBands Imagery and DataFusion

Accurate (state of art Computer Vision)

Extensible by design

Open Source



@data\_pink

[www.datapink.com](http://www.datapink.com)

# Take Away

- Industrial FOSS4G state of art GeoSpatial Imagery framework available
- Performances already OK to use it for region / small country , even on cheap GPU server, scale if you provide better hardware...
- No need anymore to be a Computer Vision expert to use it
- Plain OpenData can be use to train accurate model
- Pixel accurate labelled training OpenDataSet will be a game changer  
=> BoF 15:00 Kleiner Horsall